

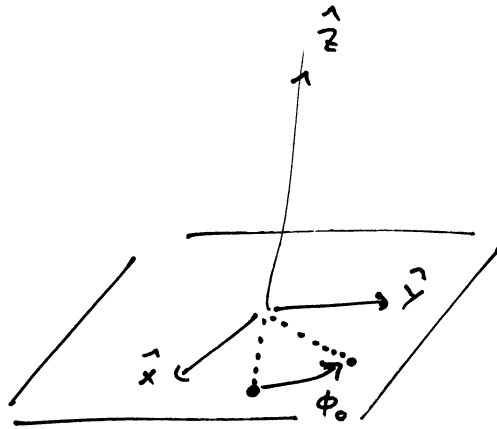
# Theory of angular momentum

Review of last week:

2D rotation of a classical state:

$$\begin{pmatrix} x \\ y \end{pmatrix} \xrightarrow{R(\phi_0 \hat{z})} \begin{pmatrix} x' \\ y' \end{pmatrix}$$

$$\begin{pmatrix} p_x \\ p_y \end{pmatrix} \xrightarrow{R(\phi_0 \hat{z})} \begin{pmatrix} p_{x'} \\ p_{y'} \end{pmatrix}$$



2D rotation of a **quantum state**:

$$U[R(\epsilon \hat{z})] = \mathbb{1} - \frac{i\epsilon}{\hbar} L_z$$

$\phi_0 = \epsilon \ll 1$

$$U[R(\phi_0 \hat{z})] : |\psi\rangle \rightarrow |\psi_R\rangle$$

$$L_z = X P_y - Y P_x$$

$$U[R(\phi_0 \hat{z})] \xrightarrow{\{|\psi, \phi\rangle\} \text{ basis}} \exp(-\phi_0 \frac{\partial}{\partial \phi})$$

$$\exp(-\phi \frac{\partial}{\partial \phi}) \psi(r, \phi) = \psi(r, \phi - \phi_0)$$

Eigenvalue problem of  $L_z$ :

$$L_z |\ell_z\rangle = \ell_z |\ell_z\rangle$$

↓ coordinate basis  $\psi_{\ell_z}(r, \phi) \equiv \langle \psi, \phi | \ell_z \rangle$

$$-i\hbar \frac{\partial}{\partial \phi} \psi_{\ell_z}(r, \phi) = \ell_z \psi_{\ell_z}(r, \phi)$$

EIGENVALUES  $\ell_z = m\hbar$ ,  $m = 0, \pm 1, \pm 2, \dots$

EIGENFUNCTIONS  $\psi_{\ell_z}(r, \phi) = R(r) e^{im\phi}$

## Rotational invariant Hamiltonian H

$$[H, L_z] = 0 \Rightarrow \text{common eigenbasis}$$



$R(\varphi)$  determined from the eigenvalue problem of H

$$\left\{ -\frac{\hbar^2}{2\mu} \left( \frac{d^2}{d\varphi^2} + \frac{1}{\rho} \frac{d}{d\rho} - \frac{m^2}{\rho^2} \right) + V(\varphi) \right\} R(\rho) = E R(\rho)$$



specifies a unique solution

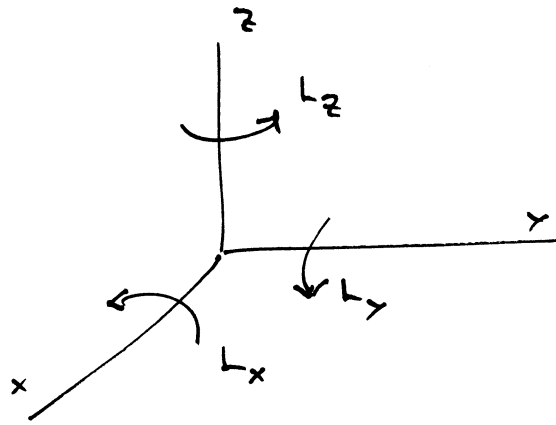
$$\Psi_{E,m} = \underbrace{R_{E,m}(\varphi)}_{\frac{1}{\sqrt{2\pi}} R(\varphi)} \underbrace{\Phi_m(\phi)}_{\frac{1}{\sqrt{2\pi}} e^{im\phi}}$$

3D

$$L_x = YP_z - ZP_y$$

$$L_y = ZP_x - XP_z$$

$$L_z = XP_y - YP_x$$



$L_x, L_y, L_z$  implement the infinitesimal rotations in Hilbert space

⇓

ANGULAR MOMENTUM COMMUTATION RELATIONS  
("SU(2) algebra")

$$[L_i, L_j] = i\hbar \varepsilon_{ijk} L_k, \quad i, j, k = x, y \text{ or } z$$

$$L^2 = |\vec{L}|^2 = L_x^2 + L_y^2 + L_z^2$$

$$[L^2, L_i] = 0, \quad i = x, y \text{ or } z$$

## Rotational invariance in 3D

$$\langle \Psi_R | H | \Psi_R \rangle = \langle \Psi | H | \Psi \rangle$$

$$\Downarrow$$

$$U^\dagger[R] H U[R] = H$$

$$\Downarrow$$

$$[H, L_i] = 0, \quad i = x, y \text{ or } z$$

$$\Downarrow [L_i, L^2] = 0$$

$$[H, L^2] = 0$$

$H, L_z, L^2$  compatible

together specify a unique basis

Start with the **eigenvalue problem of  $L_z$  and  $L^2$**

In 2D we used a coordinate basis:  $|\psi\rangle \longrightarrow \psi(r, \phi) \equiv \langle r, \phi | \psi \rangle$

Now, in 3D, let's try to work directly in the eigenbasis  
(cf. Dirac's approach to the HO)

$$L^2 |\alpha, \beta\rangle = \alpha |\alpha, \beta\rangle$$

$$L_z |\alpha, \beta\rangle = \beta |\alpha, \beta\rangle$$

$$L_{\pm} \equiv L_x \pm iL_y \quad \text{LADDER OPERATORS}$$

$$[L_z, L_{\pm}] = \pm \hbar L_{\pm} \Rightarrow \text{shifts the eigenvalue of } L_z \text{ by } \pm \hbar$$

$$[L^2, L_{\pm}] = 0 \Rightarrow \text{eigenvalues of } L^2 \text{ insensitive to } L_{\pm}$$

$$\begin{aligned} \text{Ex } L_z(L_+|\alpha, \beta\rangle) &= (L_+L_z + [L_z, L_+])|\alpha, \beta\rangle \\ &= (L_+L_z + \hbar L_+)|\alpha, \beta\rangle \\ &= (\beta + \hbar)(L_+|\alpha, \beta\rangle) \end{aligned}$$

$$L_+|\alpha, \beta\rangle = C_+(\alpha, \beta) |\alpha, \beta + \hbar\rangle \quad \underbrace{C_+(\alpha, \beta) |\alpha, \beta + \hbar\rangle}_{C_+(\alpha, \beta) |\alpha, \beta + \hbar\rangle}$$

$$L_-|\alpha, \beta\rangle = C_-(\alpha, \beta) |\alpha, \beta - \hbar\rangle$$

Let's have a closer look!  
**BLACK BOARD!**  $\rightarrow$

$$\alpha = \beta_{\max} (\beta_{\max} + \hbar)$$

$$\beta_{\max} = \frac{\hbar k}{2}, \quad k = 0, +1, +2, \dots$$

$$-\beta_{\max} \leq \beta \leq \beta_{\max}$$

$L_z$  can have half-integral eigenvalues!

$$\langle \alpha\beta | L^2 - L_z^2 | \alpha\beta \rangle = \langle \alpha\beta | \underbrace{L_x^2 + L_y^2}_{\text{positive definite operators}} | \alpha\beta \rangle \geq 0$$

$$\Rightarrow \alpha - \beta^2 \geq 0 \Rightarrow \alpha \geq \beta^2$$

⇓

$$\exists |\alpha, \beta_{\max}\rangle : L_+ |\alpha, \beta_{\max}\rangle = 0$$

$$|\alpha, \beta_{\min}\rangle : L_- |\alpha, \beta_{\min}\rangle = 0$$

Start with the  
"top state"

$$0 = L_- L_+ |\alpha, \beta_{\max}\rangle = (L^2 - L_z^2 - \hbar L_z) |\alpha, \beta_{\max}\rangle$$

$$= (\alpha - \beta_{\max}^2 - \hbar \beta_{\max}) |\alpha, \beta_{\max}\rangle = 0$$

$$\Rightarrow \alpha = \beta_{\max} (\beta_{\max} + \hbar) \quad (1)$$

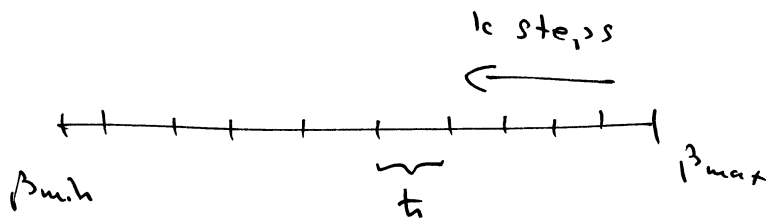
Now operate  $\hbar$  times with  $L_-$  till we reach  $|\alpha, \beta_{\min}\rangle$ .

Use that  $L_- |\alpha, \beta_{\min}\rangle = 0$

$$\Rightarrow 0 = L_+ L_- |\alpha, \beta_{\min}\rangle = (L^2 - L_z^2 + \hbar L_z) |\alpha, \beta_{\min}\rangle$$

$$\Rightarrow \alpha = \beta_{\min} (\beta_{\min} - \hbar) \quad (2)$$

$$(1) \& (2) \Rightarrow \beta_{\min} = -\beta_{\max} \Rightarrow 2\beta_{\max} = \beta_{\max} - \beta_{\min} = tk$$



$$1) \quad \boxed{-\beta \leq \beta \leq \beta_{\max}}$$

$$\beta_{\max} = \frac{tk}{2}, \quad k=0, 1, 2, \dots$$

$$\boxed{\alpha = (\beta_{\max}) (\beta_{\max} + t) = t^2 \frac{k}{2} \left( \frac{k}{2} + 1 \right)}$$

$L_2$  can have half-integral eigenvalues! 🤯

cf. to the 2D analysis:

$$\beta = \mathcal{L}_z = m\hbar, \quad m = 0, \pm 1, \pm 2, \dots$$

?

In the 3D analysis we relied only on the commutation relations

$$[L_z, L_{\pm}] = \pm \hbar L_{\pm}, \quad [L^2, L_{\pm}] = 0$$

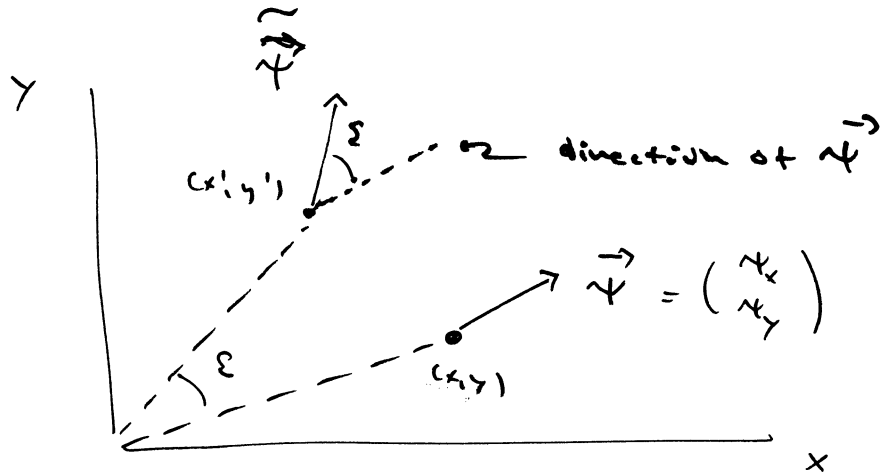
**no** projection onto a coordinate basis

↳ with only scalar wave functions

$$\psi(x, y, z) = \langle x y z | \psi \rangle$$

The half-integral eigenvalues of  $L_z$  reflect the possibility of having **multicomponent wave functions**. The components get shuffled around when doing a rotation. The "shuffling around" is governed by a **spin operator**. *blackboard!*



EXAMPLE

$$\begin{pmatrix} x \\ y \end{pmatrix} \xrightarrow{R} \begin{pmatrix} x' \\ y' \end{pmatrix}$$

SCALAR WAVE FUNCTION

$$\cup [R] : \psi(x, y) \rightarrow \tilde{\psi}(x, y), \quad \tilde{\psi}(x', y') = \psi(x, y)$$

2-COMPONENT WAVE FUNCTION TRANSFORMING AS A VECTOR

$$\begin{pmatrix} \psi_x(x, y) \\ \psi_y(x, y) \end{pmatrix} \xrightarrow[\text{OF } \vec{\psi}]{\text{ROTATE THE COMPONENTS}} \begin{pmatrix} \cos \varepsilon & -\sin \varepsilon \\ \sin \varepsilon & \cos \varepsilon \end{pmatrix} \begin{pmatrix} \psi_x(x, y) \\ \psi_y(x, y) \end{pmatrix}$$

$$\underset{\approx}{\text{INFINITESIMAL ROTATION}} \begin{pmatrix} 1 & -\varepsilon \\ \varepsilon & 1 \end{pmatrix} \begin{pmatrix} \psi_x(x, y) \\ \psi_y(x, y) \end{pmatrix}$$

$$= \begin{pmatrix} \psi_x(x, y) - \varepsilon \psi_y(x, y) \\ \varepsilon \psi_x(x, y) + \psi_y(x, y) \end{pmatrix} \xrightarrow[\text{OF } \psi_x, \psi_y]{\text{ROTATE THE ARGUMENTS}}$$

PS  
Lecture  
Notes  
last week

$$\begin{pmatrix} \Psi_x(x+y\varepsilon, y-x\varepsilon) - \varepsilon \Psi(x+y\varepsilon, y-x\varepsilon) \\ \varepsilon \Psi_x(x+y\varepsilon, y-x\varepsilon) + \Psi_y(x+y\varepsilon, y-x\varepsilon) \end{pmatrix}$$

$$= \begin{pmatrix} \tilde{\Psi}_x(x, y) \\ \tilde{\Psi}_y(x, y) \end{pmatrix}$$

$\Downarrow$

$$\begin{pmatrix} \tilde{\Psi}_x(x, y) \\ \tilde{\Psi}_y(x, y) \end{pmatrix} = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \frac{i\varepsilon}{\hbar} \begin{pmatrix} L_z & 0 \\ 0 & L_z \end{pmatrix} - \frac{i\varepsilon}{\hbar} \begin{pmatrix} 0 & -i\hbar \\ i\hbar & 0 \end{pmatrix} \right\} \times \begin{pmatrix} \Psi_x(x, y) \\ \Psi_y(x, y) \end{pmatrix}$$

$S_z$   
 $\downarrow$

$$\Rightarrow \left( \mathbb{1} - \frac{i\varepsilon}{\hbar} J_z \right) \begin{pmatrix} \Psi_x(x, y) \\ \Psi_y(x, y) \end{pmatrix} = \begin{pmatrix} \tilde{\Psi}_x(x, y) \\ \tilde{\Psi}_y(x, y) \end{pmatrix}$$

$$J_z = L_z \overset{(1)}{\uparrow} \otimes \mathbb{1} \overset{(2)}{\uparrow} + \mathbb{1} \overset{(1)}{\uparrow} \otimes S_z \overset{(2)}{\uparrow}$$

w.r.t. TO ARGUMENTS

w.r.t. COMPONENTS

Comments

- ① Origin? Relativistic, Dirac equation ...
  - ②  $S_z$  off-diagonal?! But this is a vector wave function we are looking at, not a spinor ... Also, the basis is not diagonal w.r.t.  $S_z$  (obviously!)
  - ③ Spin is not like a top spinning around its axis ...
- Prove about this later...

$$\vec{J} = \vec{L} + \vec{S} \quad \leftarrow \text{spin ("intrinsic angular momentum")}$$

total angular momentum    orbital angular momentum

$$[J_i, J_k] = i\hbar \epsilon_{ijk} J_k$$

$$[L_i, S_j] = 0$$

$i, j, k = x, y \text{ or } z$

$$\Rightarrow [S_i, S_j] = i\hbar \epsilon_{ijk} S_k$$

particles with spin



wave functions more complicated than scalars

spinors, vectors, ...

electron                       $w, z, \dots$

Back to the eigenvalue problem of  $L_z$  and  $L^2$ !

Summary of what we've found:

$$J^2 |jm\rangle = j(j+1)\hbar^2 |jm\rangle, \quad j = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$$

$$J_z |jm\rangle = m\hbar |jm\rangle, \quad m = -j, -j+1, \dots, j$$

$$\beta = m\hbar, \quad \alpha = j(j+1)\hbar^2$$

If no spin  $\Rightarrow \vec{J} = \vec{L}$

$$L^2 |l m\rangle = l(l+1)\hbar^2 |l m\rangle, \quad l = 0, 1, 2, \dots$$

$$L_z |l m\rangle = m\hbar |l m\rangle, \quad m = -l, -l+1, \dots, l$$

Recall:  $L_{\pm} |\alpha \beta\rangle = C_{\pm}(\alpha \beta) |\alpha, \beta \pm \hbar\rangle$

$\alpha \rightarrow j$   
 $\beta \rightarrow m$   $\Downarrow$  add spin

$$J_{\pm} |j m\rangle = C_{\pm}(j m) |j, m \pm 1\rangle$$

$\downarrow$  some algebra (see Sakurai, p. 191 f)

$$C_{\pm}(j m) = \hbar \sqrt{(j \pm m)(j \mp m + 1)}$$

Matrix elements of  $J_x, J_y, J_z$  in the eigenbasis of  $J_z$  and  $J^2$

(Sakurai, p. 192 f)

$$\langle j' m' | J_x | j m \rangle = \langle j' m' | \frac{1}{2}(J_+ + J_-) | j m \rangle = \dots$$

$$\langle j' m' | J_y | j m \rangle = \langle j' m' | \frac{1}{2i}(J_+ - J_-) | j m \rangle = \dots$$

$$\langle j' m' | J_z | j m \rangle = m\hbar \delta_{mm'} \delta_{jj'}$$

$$\langle j' m' | J^2 | j m \rangle = j(j+1)\hbar^2 \delta_{mm'} \delta_{jj'}$$

# MATRIX REPRESENTATION IN THE $J_z - J^2$ EIGENBASIS

$J_z$  and  $J^2$  diagonal.

$$J_x \rightarrow \begin{bmatrix} |0\rangle & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & 0 & \hbar/2 & 0 & 0 & 0 & \\ 0 & \hbar/2 & 0 & 0 & 0 & 0 & \\ 0 & 0 & 0 & 0 & \hbar/2^{1/2} & 0 & \\ 0 & 0 & 0 & \hbar/2^{1/2} & 0 & \hbar/2^{1/2} & \\ 0 & 0 & 0 & 0 & \hbar/2^{1/2} & 0 & \\ \vdots & & & & & & \ddots \end{bmatrix}$$

$$J_y \rightarrow \begin{bmatrix} |0\rangle & 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & 0 & -i\hbar/2 & 0 & 0 & 0 & \\ 0 & i\hbar/2 & 0 & 0 & 0 & 0 & \\ 0 & 0 & 0 & 0 & -i\hbar/2^{1/2} & 0 & \\ 0 & 0 & 0 & i\hbar/2^{1/2} & 0 & -i\hbar/2^{1/2} & \\ 0 & 0 & 0 & 0 & i\hbar/2^{1/2} & 0 & \\ \vdots & & & & & & \ddots \end{bmatrix}$$

$J_x$  and  $J_y$  block diagonal!

$$[J_i^{(j)}, J_k^{(j)}] = i\hbar \epsilon_{ijk} J_l^{(j)}, \quad j = 0, 1/2, 1, \dots$$

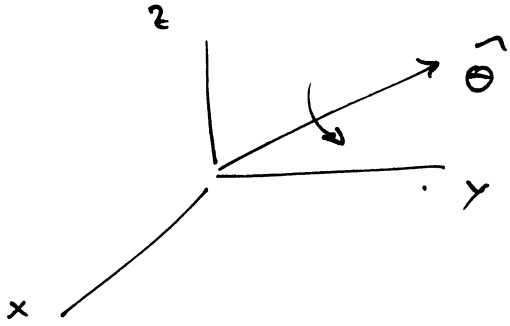
satisfied within each  $(2j+1) \times (2j+1)$  block  
 irreducible rep of  $\vec{J}$

The rotation matrices characterized by a definite  $j$  form a unitary group: **SU(2)**

$\ni$  INVERSE, IDENTITY ELEMENT,  
 PRODUCT RULE (matrix algebra)

### What about finite rotations?

$$U[R(\hat{\theta})] = \lim_{N \rightarrow \infty} \left( 1 - \frac{i}{\hbar} \underbrace{\left( \frac{\theta}{N} \right)}_{\hat{\theta} \cdot \vec{J}} \right)^N = e^{-i\hat{\theta} \cdot \vec{J} / \hbar}$$



ROTATION WITH AN ANGLE  $\theta$  ABOUT  $\hat{\theta}$

$J_j$  block diagonal  $\Rightarrow \hat{\theta} \cdot \vec{J}$  block diagonal  
 $\Rightarrow U[R(\hat{\theta})]$  block diagonal

$$\mathcal{D}^{(j)}[R] \quad \text{jth block}$$

To rotate  $|u_j\rangle$  we only need to use  $\mathcal{D}^{(j)}[R]$  ↙ "invariant subspaces"

More generally: if  $|\psi\rangle$  has components only in  $V_0, V_1, V_2, \dots, V_j$   
 ( $V_j$  spanned by  $|m=j, j\rangle, \dots, |m=-j, j\rangle$ ), we only need the first  $j+1$  matrices

$$\mathcal{D}^{(0)}[R], \dots, \mathcal{D}^{(j)}[R]$$

$$\begin{aligned}
D^{(j)}[R(\theta)] &= \exp\left(-i \frac{\vec{\theta} \cdot \vec{J}^{(j)}}{\hbar}\right) \\
&= \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{-i\theta}{\hbar}\right)^n (\hat{\theta} \cdot \vec{J}^{(j)})^n \\
&= \sum_{n=0}^{2j} f_n(\theta) (\hat{\theta} \cdot \vec{J}^{(j)})^n
\end{aligned}$$



can be calculated  
 Sakurai, sec. 3.8  
 (not included in the course)

Within each invariant subspace  $V_j$ ,  $H$  has the same eigenvalue  $E_j$ , since  $[H, J_z] = 0$



all states of a given  $j$  are degenerate in energy

Now... let's look at the

## Angular momentum eigenfunctions in the coordinate basis



Sakurai, 3.6

### summary

$$L_{\pm} \equiv L_x \pm iL_y \quad \overbrace{\{ |r, \theta, \phi\rangle \}}^{\text{spherical coordinate basis}} \rightarrow \pm \hbar e^{\pm i\phi} \left( \frac{\partial}{\partial \theta} \pm i \cot \theta \frac{\partial}{\partial \phi} \right)$$

Start with the "highest-weight state"  $|m=l, l\rangle$

$$L_+ |l, l\rangle = 0$$

$$\langle r, \theta, \phi | L_+ |l, l\rangle = \left( \frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \overbrace{\Psi_l^l(r, \theta, \phi)}^{\langle r, \theta, \phi | l, l \rangle} = 0$$

$\Psi_l^l$  eigenfunctions of  $L_z$

$$\Psi_l^l(r, \theta, \phi) = U_l^l(r, \theta) e^{i l \phi}$$

FEED BACK IN !

$$\Rightarrow \left( \frac{\partial}{\partial \theta} - l \cot \theta \right) U_l^l = 0$$

$$\Rightarrow \frac{dU_l^l}{U_l^l} = l \frac{d(\ln \sin \theta)}{\sin \theta}$$

$$\Rightarrow U_l^l(r, \theta) = R(r) (\sin \theta)^l$$

$\hat{L}$  ARBITRARY NORMALIZABLE FUNCTION



Suppose there's no r-dependence:

⇓ NORMALIZATION

$$R(r) = (-1)^l \left( \frac{(2l+1)!}{4\pi} \right)^{1/2} \frac{1}{2^l l!}$$

EIGENFUNCTION TO  $L_z$  AND  $L^2$  ( $m=l$ )

$$Y_{l,l}^m(\theta, \phi) = (-1)^l \left( \frac{(2l+1)!}{4\pi} \right)^{1/2} \frac{1}{2^l l!} (\sin\theta)^l e^{il\theta}$$

$$\int Y_{l,l}^{l*}(\theta, \phi) Y_{l,l}^l(\theta, \phi) d\Omega = 1 \quad \text{CHECK!}$$

Apply  $L_-$  ( $l-m$ ) times to  $|l,l\rangle$

EIGENFUNCTIONS  
FOR  $m \geq 0$

⇓

repeat the analysis

$$Y_{l,l}^m(\theta, \phi) = (-1)^l \left( \frac{(2l+1)!}{4\pi} \right)^{1/2} \frac{1}{2^l l!} \left( \frac{(l+m)!}{(2l)! (l-m)!} \right)^{1/2}$$

$$\times e^{im\phi} (\sin\theta)^{-m} \frac{d^{l-m}}{d(\cos\theta)^{l-m}} (\sin\theta)^{2l}$$

**SPHERICAL HARMONICS**

For  $m < 0$ , use

$$Y_{l,l}^{-m} = (-1)^m \left( Y_{l,l}^m \right)^*, \quad m \geq 0$$

But suppose there *is* an r-dependence!

Large degeneracy! How to "nail down"  $R(r)$  ?

Bring in  $H$  ! Works fine if  $H$  is rotationally invariant...

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} [H, L_z] = [H, L^2] = 0$$

Eigenvalue problem for  $H$  ("time-independent Schrödinger eq.")

$$H |E_{m\ell}\rangle = E |E_{m\ell}\rangle$$

$\{ |r\theta\phi\rangle \}$   
basis



$\leftarrow = |m\ell\rangle$  "split by  $E$ "

ROTATIONAL INVARIANCE  $\Rightarrow$  NO  $\theta, \phi$  IN  $V$

$$\left\{ -\frac{\hbar^2}{2\mu} \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} \sin\theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2}{\partial \phi^2} \right) + V(r) \right\}$$

$$\ast \Psi_{E_{m\ell}}(r, \theta, \phi) = E \Psi_{E_{m\ell}}(r, \theta, \phi)$$

$$\Psi_{E_{m\ell}} = \langle r\theta\phi | E_{m\ell} \rangle$$

$$\text{FEED IN } \Psi_{E_{m\ell}}(r, \theta, \phi) = R_{E_{m\ell}}(r) Y_{\ell}^m(\theta, \phi)$$



## " RADIAL EQUATION "

$$\left\{ -\frac{\hbar^2}{2\mu} \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} - \frac{l(l+1)}{r^2} \right) + V(r) \right\} R_{El} = E R_{El}$$

effective centrifugal potential  
from the orbital angular momentum

$$\Downarrow U_{El} \equiv r R_{El}$$

$$\left( -\frac{\hbar^2}{2\mu} \frac{d^2}{dr^2} + V(r) + \frac{l(l+1)\hbar^2}{2\mu r^2} \right) U_{El} = E U_{El}$$

use that  $\mathcal{D}_l$  is Hermitian, and require  $U_{El}$  to be normalizable

$$U_{El} \xrightarrow{r \rightarrow 0} 0, \quad U_{El} \xrightarrow{r \rightarrow \infty} \begin{cases} 0, & E < 0 \\ e^{ikr}, & E > 0 \end{cases}$$

BOUND STATE

UNBOUND STATE

## Paradigm cases

**Free particle**  $H = -\frac{\hbar^2}{2\mu} \nabla^2$

$$\psi_{\mathbb{E}}(x, y, z) = \frac{1}{(2\pi\hbar)^{3/2}} e^{i\vec{p} \cdot \vec{r} / \hbar}, \quad \mathbb{E} = \frac{p^2}{2\mu} = \frac{(\hbar k)^2}{2\mu}$$

spherical coordinates

$$\psi_{\mathbb{E} \ell m}(r, \theta, \phi) = j_{\ell}(kr) Y_{\ell}^m(\theta, \phi), \quad \mathbb{E} = \frac{(\hbar k)^2}{2\mu}$$

$\hat{L}$  SPHERICAL BESSEL FUNCTION OF ORDER  $\ell$

**(Isotropic) harmonic oscillator**

$$H = -\frac{\hbar^2}{2\mu} \nabla^2 + \frac{1}{2} \mu \omega^2 (x^2 + y^2 + z^2)$$

$$\psi_{\mathbb{E} \ell m}(r, \theta, \phi) = \frac{U_{\mathbb{E} \ell}(r)}{r} Y_{\ell}^m(\theta, \phi)$$

$$\gamma \equiv \left(\frac{\mu \omega}{\hbar}\right)^{1/2} r$$

$$U_{\mathbb{E} \ell}(r) = e^{-\gamma^2/2} v(\gamma)$$

$$v(\gamma) = \gamma^{\ell+1} \sum_{n=0}^{\infty} C_n \gamma^n$$

can be determined  
recursively