

Solutions/answers to selected problems of the exam
12:th of April in Dynamical Systems 2017

CHALMERS, GÖTEBORGS UNIVERSITET

EXAM for
DYNAMICAL SYSTEMS

COURSE CODES: **TIF 155, FIM770GU, PhD**

Time:	April 12, 2017, at 14 ⁰⁰ – 18 ⁰⁰
Place:	Johanneberg
Teachers:	Kristian Gustafsson, 070-050 2211 (mobile), visits once at 15 ⁰⁰
Allowed material:	Mathematics Handbook for Science and Engineering
Not allowed:	any other written material, calculator

Maximum score on this exam: 12 points (need 5 points to pass).

Maximum score for homework problems: 24 points (need 10 points to pass).

CTH ≥ 20 passed; ≥ 27 grade 4; ≥ 32 grade 5,

GU ≥ 20 grade G; ≥ 29 grade VG.

1. Short questions [2 points] For each of the following questions give a concise answer within a few lines per question.

- What defines a conservative dynamical system?
- What is the difference between a conservative dynamical system and a Hamiltonian dynamical system?
- Explain the main differences between a supercritical and a subcritical bifurcation.
- Explain what a Hopf bifurcation is.
- State three properties of the index of a curve, I_C .
- Explain what a fractal (strange) attractor is.
- What conditions must be satisfied for a system to show a fractal (strange) attractor?
- What is the significance of the parameter q in the generalized dimension spectrum D_q ?

2. Bifurcation [2 points] Consider the dynamical system

$$\begin{aligned}\dot{x} &= ax + y + x^3 \\ \dot{y} &= x - y,\end{aligned}\tag{1}$$

with a real parameter a .

- Find all fixed points of the system (1) and give conditions on a for which the fixed points exist.
- Use linear stability analysis to classify the fixed points you found in subtask a) as functions of the parameter a .
- Plot the bifurcation diagram for one of the components of the fixed points, for example x^* , against the parameter a . Label each branch plotted with the type of fixed point you found in the classification in subtask b). What kind of bifurcation(s) do you obtain?

3. Non-linear stability analysis and phase portrait [2 points] Consider the system

$$\begin{aligned}\dot{x} &= y - xy^2 \\ \dot{y} &= -x + yx^2.\end{aligned}\tag{2}$$

- Find all fixed points of the system (2).
- What does linear stability analysis predict about the fixed point(s)?
- Sketch the phase-plane dynamics in the region $-2 \leq x \leq 2$ and $-2 \leq y \leq 2$. In order to do this, it may be helpful to express the dynamics in polar coordinates.
- Classify the fixed point at the origin for the non-linear system (2).

4. Infinite-period bifurcation [2 points] Consider a dynamical system in spherical coordinates

$$\begin{aligned}\dot{r} &= r - r^3 \\ \dot{\theta} &= \mu - \sin \theta,\end{aligned}$$

where $r > 0$ and μ is a real parameter.

- For $\mu < 1$ and for $\mu > 1$, find all attractors of the corresponding Cartesian dynamical system (you do not need to change to Cartesian coordinates if you do not want to).
- Describe the bifurcation that happens as μ passes unity.
- For any closed orbit(s) of the system, estimate the dependence of the period time on μ (up to a prefactor) close to $\mu = 1$.
- Give a motivation of why the time dependence you calculated in subtask c) may be useful.

5. The deformation matrix [2 points] Consider the dynamical system

$$\begin{aligned}\dot{r} &= \mu r - r^3 \\ \dot{\theta} &= \omega + \nu r^2\end{aligned}\tag{3}$$

with a real parameter μ .

In the problem sets you were supposed to show that the corresponding dynamical system in Cartesian coordinates $x = r \cos \theta$ and $y = r \sin \theta$ is

$$\begin{aligned}\dot{x} &= \mu x - y\omega - x^3 - \nu y^3 - \nu x^2 y - xy^2 \\ \dot{y} &= \omega x + \mu y + \nu x^3 - y^3 - x^2 y + \nu xy^2.\end{aligned}\tag{4}$$

The deformation matrix \mathbb{M} is defined as the matrix projecting an initial infinitesimal separation vector $\boldsymbol{\delta}(0)$ to an infinitesimal separation $\boldsymbol{\delta}(t)$ at t :

$$\boldsymbol{\delta}(t) = \mathbb{M}(t)\boldsymbol{\delta}(0).$$

The stability exponents of separations are defined as

$$\tilde{\sigma}_i \equiv \lim_{t \rightarrow \infty} \frac{1}{t} \ln m_i$$

where m_i is the i :th eigenvalue of \mathbb{M} .

- a) For the case $\mu > 0$, find the radius and period time of the attracting limit cycle in the system Eq. (3).
- b) Analytically calculate the stability exponents of separations when $\mu < 0$ (OBS: different limit compared to subtask a)) for the system (4) in Cartesian coordinates.
- c) Analytically calculate the stability exponents of separations when $\mu < 0$ for the system (3) in polar coordinates.
- d) In the problem sets you were supposed to use a relation for the transformation of the deformation matrix under a general non-singular coordinate transformation $\boldsymbol{x} = \boldsymbol{G}(\boldsymbol{y})$:

$$\mathbb{M}_{\boldsymbol{y}}(t) = \mathbb{J}_G^{-1}(\boldsymbol{y}(t))\mathbb{M}_{\boldsymbol{x}}(t)\mathbb{J}_G(\boldsymbol{y}(0)).\tag{5}$$

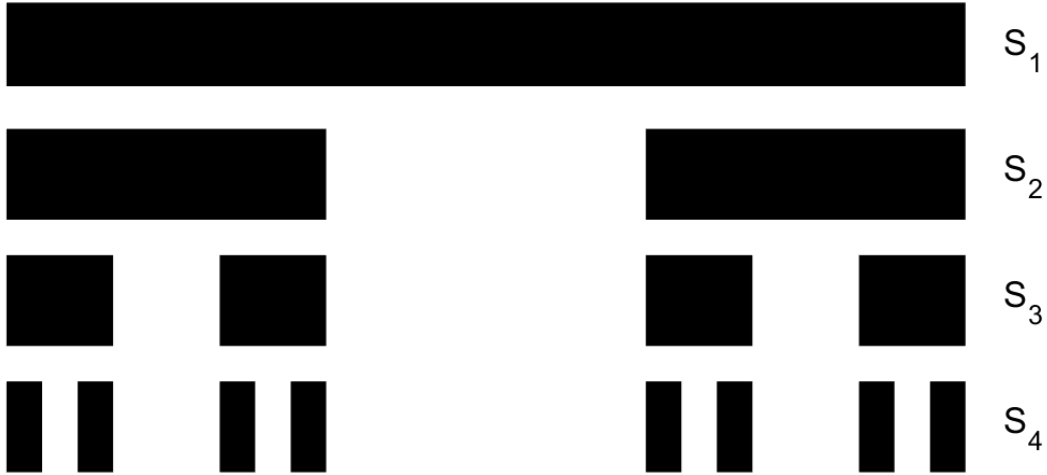
Here $\mathbb{M}_{\boldsymbol{x}}(t)$ is the deformation matrix in the original coordinates, $\mathbb{M}_{\boldsymbol{y}}(t)$ is the deformation matrix in the transformed coordinates, and $\mathbb{J}_G(\boldsymbol{y}(t))$ is the gradient matrix of the transformation \boldsymbol{G} with components

$$[\mathbb{J}_G(\boldsymbol{y}(t))]_{ij} = \frac{\partial x_i}{\partial y_j}.$$

Does the relation (5) apply to your results in subtasks b) and c)?

6. Box-counting dimension [2 points] The figures below show the first few generations S_1, S_2, S_3 and S_4 in the construction of modified versions of the *middle thirds Cantor set*. For each figure the fractal set is obtained by iterating to generation S_n with $n \rightarrow \infty$.

- a) Start by a two-dimensional strip of finite width and height. Analytically find the box-counting dimension D_0 of the fractal set, obtained by at each generation removing the middle third horizontal interval out of three equally sized horizontal intervals:



- b) Start by a two-dimensional strip of finite width and height. Analytically find the box-counting dimension D_0 of the fractal set, obtained by at each generation removing both the middle third horizontal and vertical intervals out of three equally sized horizontal and vertical intervals:



- c) Discuss how the results in subtasks a) and b) are related to the box-counting dimension of the middle-third Cantor set.