

## Home assignment 1 — Symmetry TIF310/FYM310

Deadline Friday Nov. 20, 2020.

Hand in solutions produced by  $\text{\TeX}$  by mail to martin.cederwall@chalmers.se or printed in a box outside room Origo 6102. Good luck!

- 1.1. Show that the real Lie algebra  $\mathfrak{so}(4, \mathbb{R})$  of rotations in 4 euclidean dimensions is  $\mathfrak{so}(4) \simeq \mathfrak{su}(2) \oplus \mathfrak{su}(2)$ .
- 1.2. Show that if  $\mathfrak{h}$  is an ideal in  $\mathfrak{g}$ ,  $\mathfrak{g} \text{ mod } \mathfrak{h}$  is a Lie algebra. (As a vector space,  $\mathfrak{g} \text{ mod } \mathfrak{h}$  consists of elements  $a \in \mathfrak{g}$  modulo the equivalence relations  $a \approx a + b$ , where  $b$  is any element in  $\mathfrak{h}$ .)
- 1.3. Show that  $\mathfrak{gl}(n)$  and  $\mathfrak{u}(n)$  are not semi-simple, *e.g.* by finding proper ideals.
- 1.4. If the ideals of problem 1.3 are modded out, which simple Lie algebras are obtained?
- 1.5. Consider the rank 5 simple Lie algebra  $D_5 \simeq \mathfrak{so}(10)$ . This algebra has a 54-dimensional representation. Describe it in a tensor language. (*I.e.*, describe elements in the representation module as tensors. This will require the use of some invariant tensor.)
- 1.6. Consider an “inversion” of space (or space-time), defined by

$$x^m \mapsto x'^m = \frac{x^m}{x^2} .$$

Show that a special conformal transformation, on the infinitesimal form given in the lecture notes, is obtained by first performing an inversion, then a translation, and finally an inversion.