

Lectures

Exercises/Home work problems

Ordinary differential equations

Linear dynamics

E1

Non-linear dynamics

E2

Molecular dynamics

H1a/H1b

Stochastic methods

Monte Carlo integration

E3

Metropolis algorithm

H2a/H2b

Brownian dynamics

E4

Partial differential equations

Quantum structure

E5

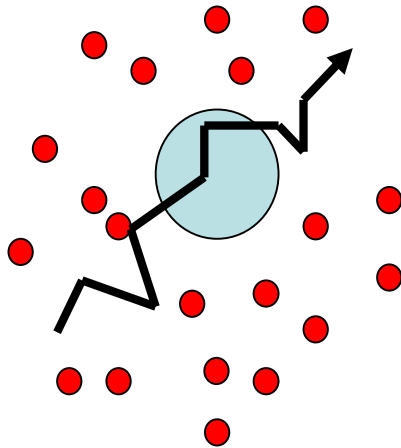
H3a

Quantum dynamics

H3b

Brownian dynamics

The erratic motion of particles dispersed in a fluid.
Observed by Brown for minute particles ejected from pollen grains.



- observed by Brown, a botanist, 1827
- key theoretical contribution by Einstein 1905
- a basic model for noise
- a standard model for a whole class of similar models
- an example of how one can take different time-scales into account and formulate a "coarse-grained" mode

Brownian dynamics

Content:

- Langevin's equation
- Fokker-Planck equation
- With an external force

Algorithm BD2

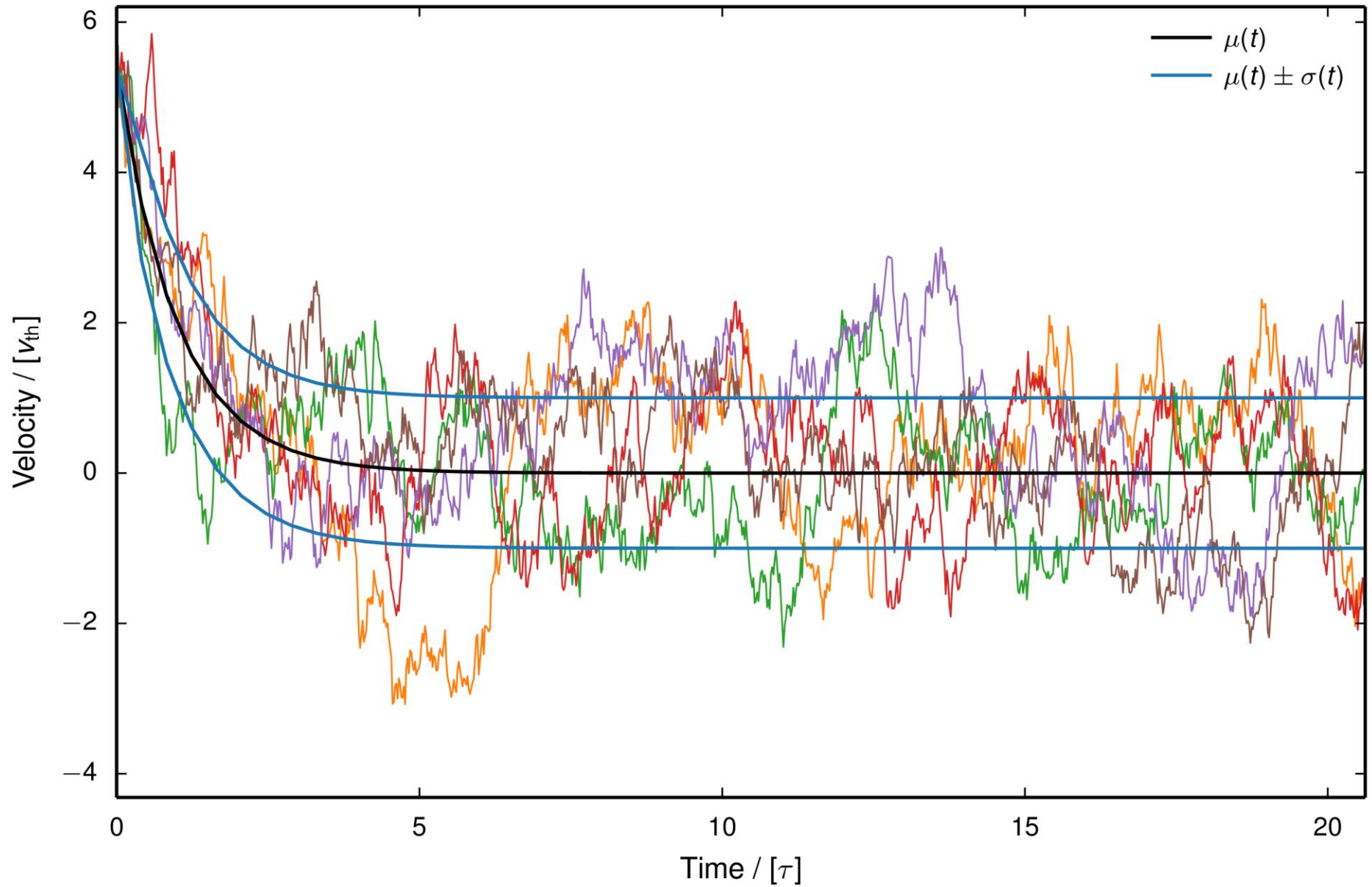
Algorithm BD2 The recommended algorithm for solving Langevin's equation is therefore

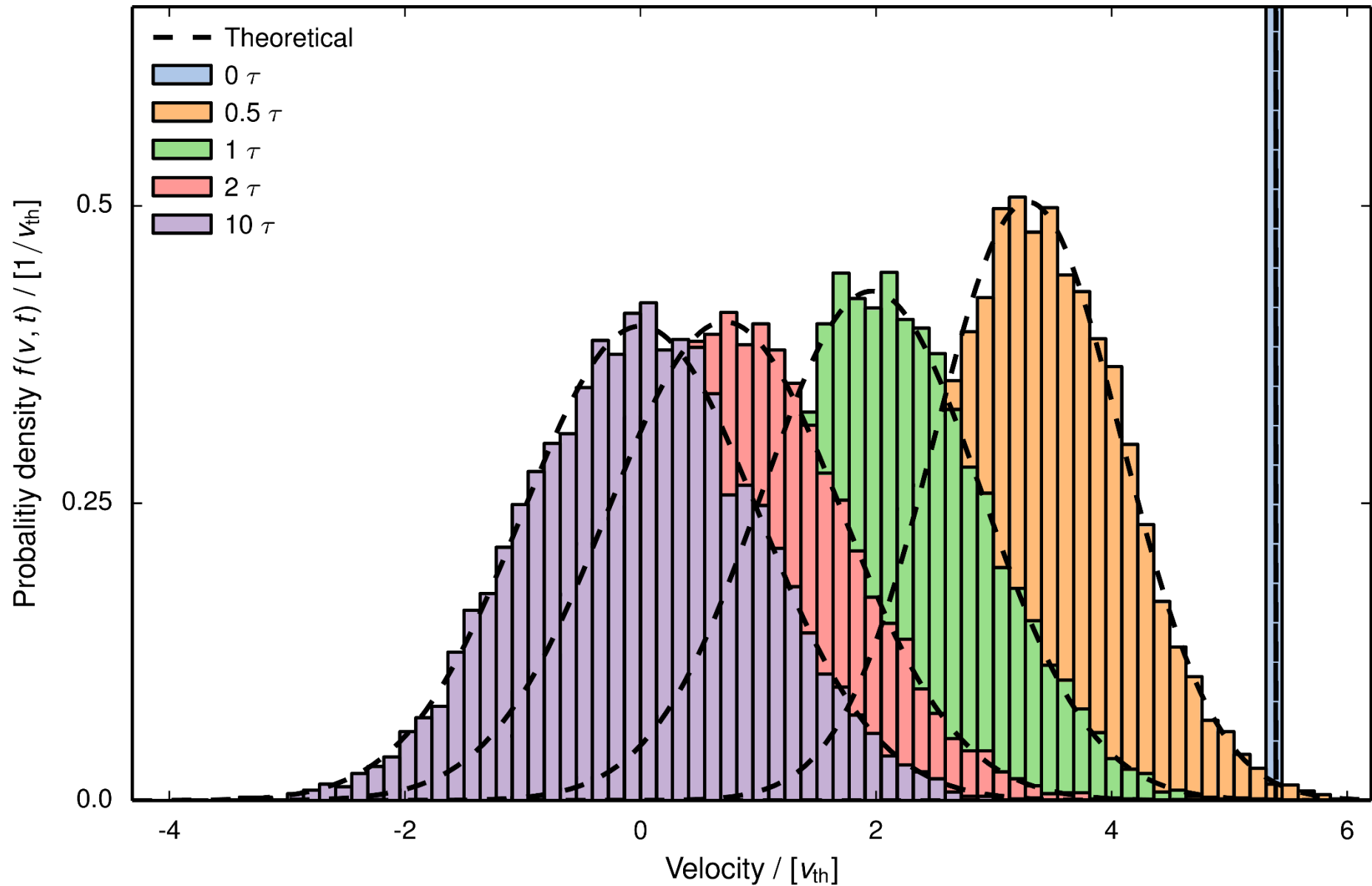
$$v_{n+1} = c_0 v_n + v_{th} \sqrt{1 - c_0^2} \mathcal{G}_n \quad (15)$$

where

$$c_0 = e^{-\eta \Delta t} \quad \text{and} \quad v_{th} = \sqrt{k_B T / m}$$

and \mathcal{G}_n is a Gaussian random number with zero mean, unit variance and uncorrelated in time $\langle \mathcal{G}_n \mathcal{G}_{n'} \rangle = \delta_{n,n'}$.





Velocity Verlet algorithm

$$v(t + \Delta t/2) = v(t^+) + \frac{1}{2}a(t)\Delta t$$

$$x(t + \Delta t) = x(t) + v(t + \Delta t/2)\Delta t$$

calculate new (external) accelerations/forces

$$v(t^- + \Delta t) = v(t + \Delta t/2) + \frac{1}{2}a(t + \Delta t)\Delta t$$

Algorithm BD3

$$v(t^+) = \sqrt{c_0}v(t) + v_{th}\sqrt{1-c_0} \mathcal{G}_1$$

$$v(t + \Delta t/2) = v(t^+) + \frac{1}{2}a(t)\Delta t$$

$$x(t + \Delta t) = x(t) + v(t + \Delta t/2)\Delta t$$

calculate new (external) accelerations/forces

$$v(t^- + \Delta t) = v(t + \Delta t/2) + \frac{1}{2}a(t + \Delta t)\Delta t$$

$$v(t + \Delta t) = \sqrt{c_0}v(t^- + \Delta t) + v_{th}\sqrt{1-c_0} \mathcal{G}_2$$

Algorithm BD3

Algorithm BD3 The Langevin's equation with an external force (acceleration) that depends on the position can be numerically solved using the following algorithm (that reduces to the velocity Verlet in the limit $\eta \rightarrow 0$):

$$\tilde{v}_{n+1} = \frac{1}{2}a_n\Delta t + \sqrt{c_0}v_n + v_{th}\sqrt{1-c_0}\mathcal{G}_{1,n}$$

$$x_{n+1} = x_n + \tilde{v}_{n+1}\Delta t$$

calculate new external accelerations/forces

$$v_{n+1} = \frac{1}{2}\sqrt{c_0}a_{n+1}\Delta t + \sqrt{c_0}\tilde{v}_{n+1} + v_{th}\sqrt{1-c_0}\mathcal{G}_{2,n}$$

where

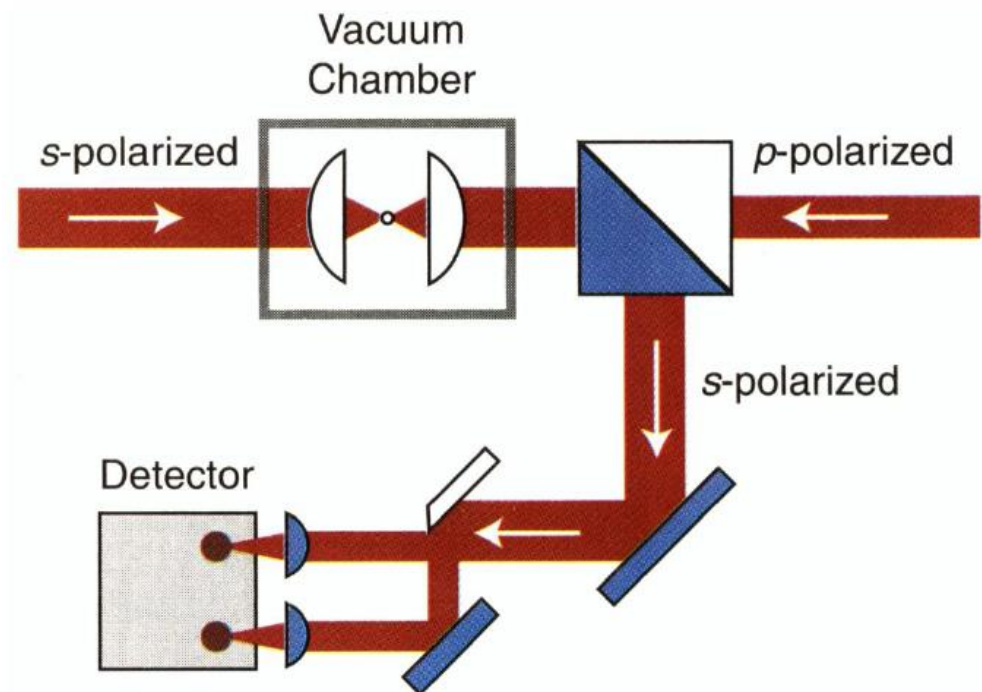
$$c_0 = e^{-\eta\Delta t} \quad \text{and} \quad v_{th} = \sqrt{k_B T/m}$$

and \mathcal{G}_1 and \mathcal{G}_2 are two independent Gaussian random numbers with zero mean, unit variance and uncorrelated in time $\langle \mathcal{G}_{1,n}\mathcal{G}_{1,n'} \rangle = \delta_{n,n'}$ and $\langle \mathcal{G}_{2,n}\mathcal{G}_{2,n'} \rangle = \delta_{n,n'}$.

Measurement of the Instantaneous Velocity of a Brownian Particle

Tongcang Li, Simon Kheifets, David Medellin, Mark G. Raizen*

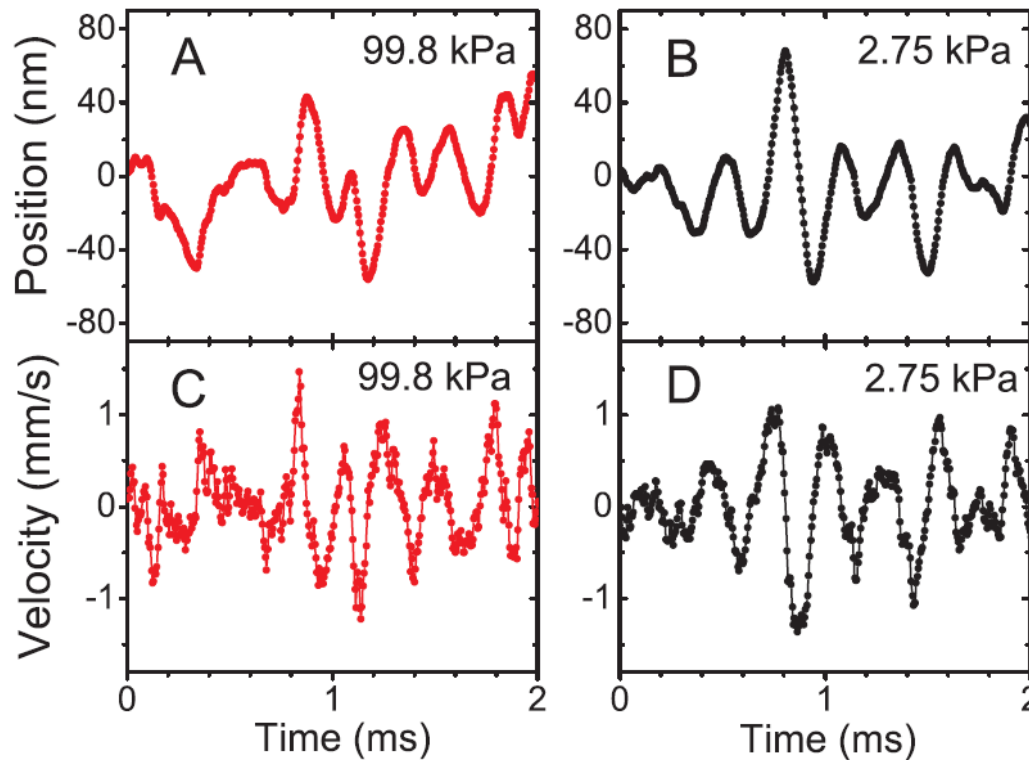
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